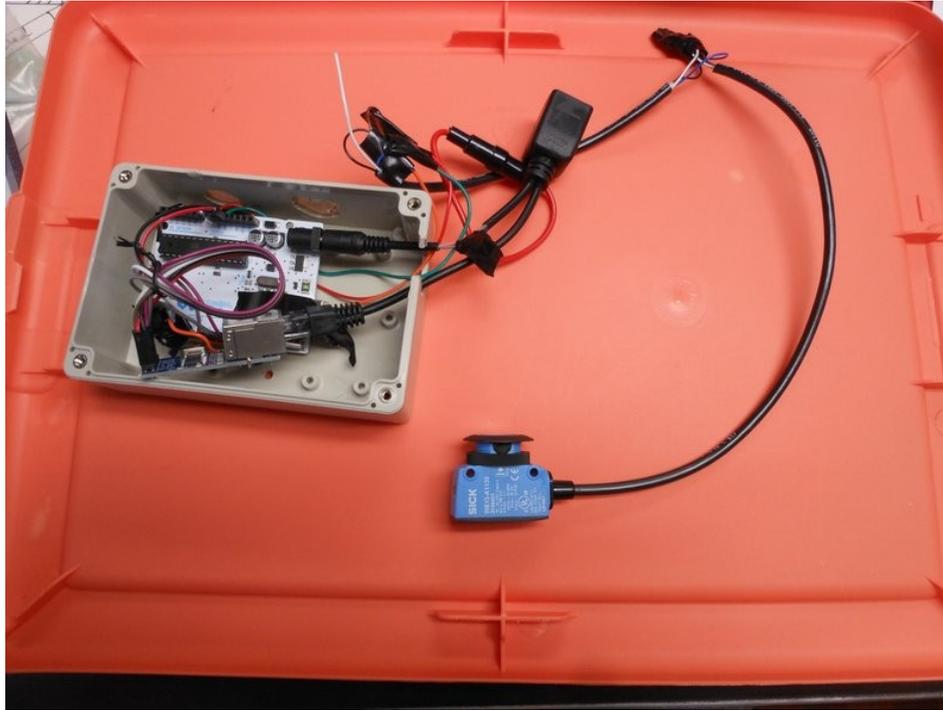


ZMHW Project

Infrared Diode Laser Motion Sensor

Objective: To make a motion sensor that acts as motion detection for Zoneminder cameras. As the cameras often have false alarms, an external sensor is a possible solution. This uses a Laser Diode Infrared Sensor.



Main half of the sensor before putting in enclosure.

Parts List:

- Arduino Uno (official recommended)(DIP recommended)
- ENC28J60 ethernet module
- Passive PoE adaptors for IP Cameras
- Series 1A fuse
- Sick WS15-D1130 Infrared Laser Diode Motion Sensor
- General Purpose Diode (I used 1N4818 diode) (may also use transistor, per data sheet for Sick)
- Jumper Wires
- Copper Wire (22-26 gauge)
- Enclosure
- Ethernet Wire
- (optional) Low Profile one and two gang wall outlet
- (optional) Blank cover plate, for one and two wall gang wall outlet
- (optional) Electrical tape (I prefer halfway decent electrical tape)
- (optional) piezo speaker
- (optional) extras of everything, in case anything fails

Work Log:

This work log will be pictures with some notes thrown in. I'll try to make note of all important parts.

Device was assembled and using the ZMHW Project source code. This is simply an Arduino sketch with UIPEthernet (to use the ENC28J60) (make sure CS is pin 10 on Uno). For more details see source code. Explaining the details is out of the spec of this doc. Simply put, the ENC28J60 is connected, the Sick sensor black wire is connected to Analog input 1, and a speaker is connected. See source code. I will try to put a fritzing diagram in the git repo.

Of importance, **Figure 1** shows two things, first off a diode connected in series with the output of the Sick sensor, and also the orange LED on the top of the sensor. The orange led will be green when there is no connection between the diodes and orange when the Laser Diodes (or LEDs) are lined up correctly. When someone moves across the field of their vision, the orange LED will change to green.

Diode on output of Sick sensor

Some laser sensors output a high or low. Some, like the Sick sensor, output a high or low (depending on whether you connect to white or black wire), however they are meant to be connected to a transistor, and thus if you connect it directly to a micro expecting it to go high or low, it will not. I dont want to deal with a transistor as I am lazy, so instead I put a 1N4819 in series with the output of the Sick sensor. TODO: pictures showing waveforms

Using the black wire, it will be normally low and go high when motion is detected (the white wire is the opposite). If you connect to a micro it will fail to go high (why?). If you put a diode on the end in series, it will turn the normally low to a noisy normally low, and sometimes it will go between 2.5-5 volts in spikes. This allows us to use the ADC to read the Sick sensor, and avoid the use of adding a transistor in. The transistor would allow for a digitalRead to be used, but we have plenty of Analog inputs to use, so let's use one of those.

It's very important to line up these sensors. If they are not lined up precisely, they will not get a sync, and the motion detection will fail. This will become important later, when we install.

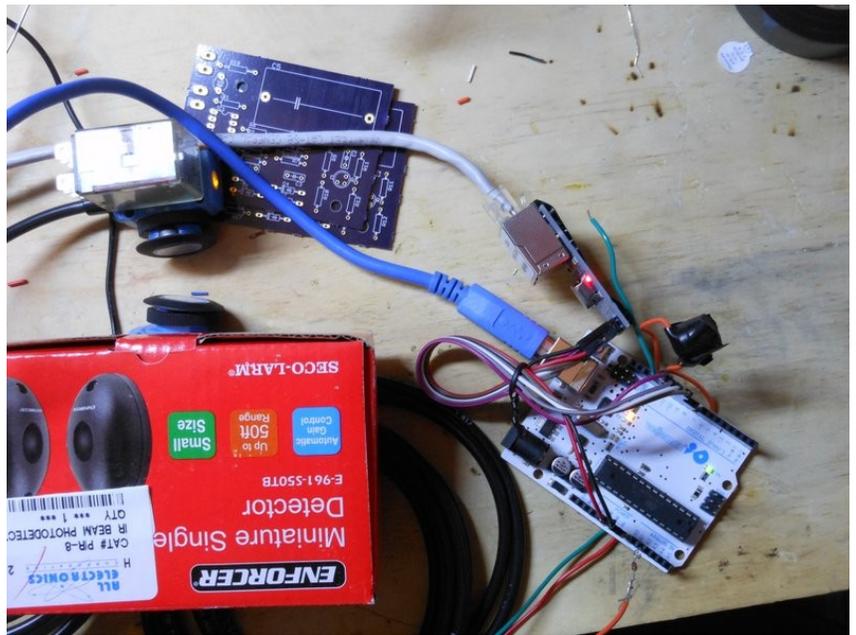


Figure 1: Orange LED on top of sensor when link detected. Series diode on output of sensor to cheat the need for transistor.

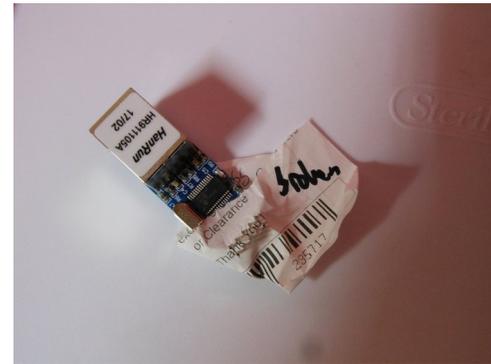


Broken ENC28J60

During my testing, I suddenly was unable to get an IP address. I checked the example sketches, then began tearing down my setup, testing another Arduino and ENC module.

It turned out, the ENC28J60 module failed on me. Make sure to buy backups.

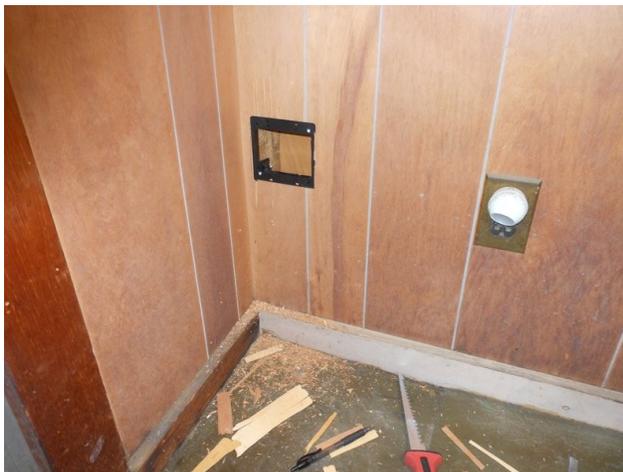
Picture Log:



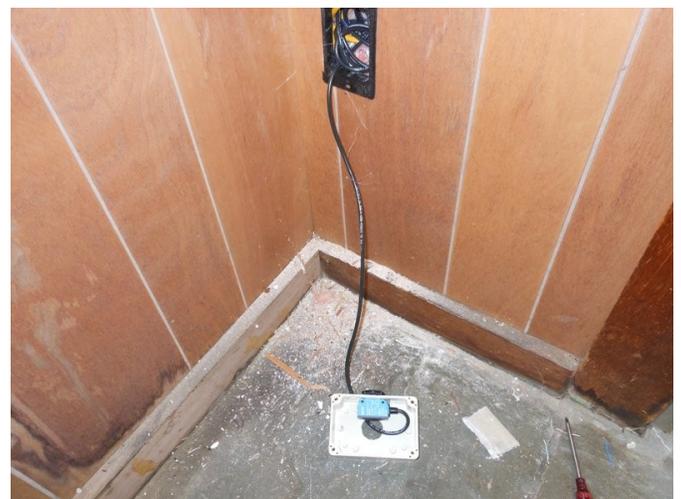
Choosing location for the sensors. Keep in mind, that the laser diode path must remain open. This is where the main board and sensor will be.



Feeding nylon string, and a wire up from the bottom of the wall to the ceiling. This is where the single sensor will be.



Low profile two gang wall plate installed.



Installing the single sensor. I used ethernet as the power line. I also used a passive PoE adapter on both sides to transfer the power onto the ethernet, and back out to a 5.5, 2.1mm barrel plug



Box installed on the wall. This is a temporary box I used for testing purposes. The additional hole at the top is an error, but allows viewing the LED (though this sensor does not change its LED colour, it's always green).

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The programs included with the Devuan GNU/Linux system are free software;
the exact distribution terms for each program are described in the
individual files in /usr/share/doc/*/*copyright.

Devuan GNU/Linux comes with ABSOLUTELY NO WARRANTY, to the extent
permitted by applicable law.
root@kali:~# sudo su
root@kali:~# ifconfig
root@kali:~# arp
          HWtype  HWaddress          Flags Mask
          ether  00:00:00:00:00:00          C
          ether  00:00:00:00:00:00          C
root@kali:~# ping 192.168.1.12
PING 192.168.1.12 (192.168.1.12) 56(84) bytes of data:
64 bytes from 192.168.1.12: icmp_seq=1 ttl=64 time=49.6 ms
^C
--- 192.168.1.12 ping statistics ---
 1 packets transmitted, 1 received, 0% packet loss, time 0ms
rtt min/avg/max/mdev = 49.698/49.698/49.698/0.000 ms
root@kali:~# arp
          HWtype  HWaddress          Flags Mask
ether      00:00:00:00:00:00          C
192.168.1.12 ether  de:ad:be:ef:11:eb          C
root@kali:~#

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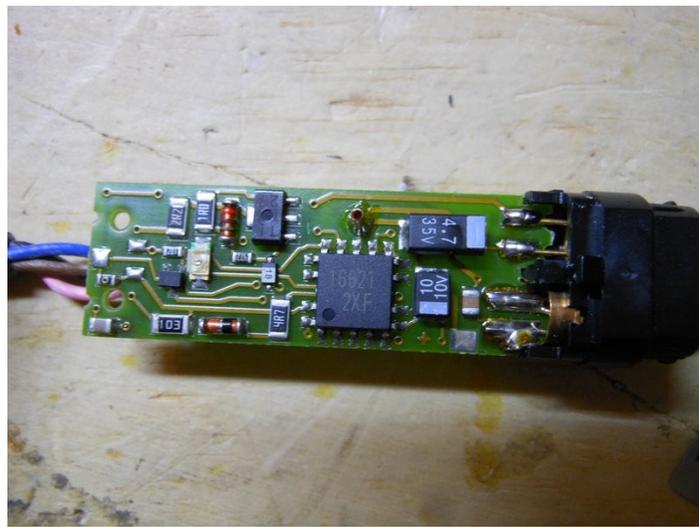
Checking the device is on the Camera LAN by pinging it, then reviewing the arp tables to make sure it's the right device (IP is static, so it's possible a conflict could arise)



This mangled web of wires, is a temporary testing ground, while I go to the store to purchase a two gang blank plate. In this setup, I will calibrate the diodes to point correctly at each other by setting this double gang receiver diode to be fixed, and then adjusting the opposite laser diode. For testing though, some electrical tape, and the power wire pulled out will do temporarily. When the lights are off, the red diode light is more visible and may be easier to calibrate.



Here's how the outlet looks just before putting the final machine screws in. It was important to buy a "non breakable" wall plate (essentially a bendable more rubberized one), as the normal wall plate, simply shattered when drilled into. The non breakable version worked well with the drill.



Omrom Motion Sensor

All electronics is also currently selling used Omrom photoelectric sensors, they are model: e3f2-r2c4. These types of photoelectric sensors are from a large catalog of different types. Some AC some DC powered. Different reaches, etc... See resources in this git repository for some PDFs.

I dismantled the device. Teardown pictures are in the photos folder. Here's an example. The devices were not easy to dismantle, and can't really be put back together as well as they were originally. However, they did seem otherwise well made. More testing will be needed on these.

Testing Attempt #2

After finding some documentation on these in the reviews, I figured out why it wasn't working for me. These opto electronics absolutely require some type of reflector opposite them. Now, not all photoelectric sensors are like this, but this Omrom model is. I've also purchased low cost ebay photoelectric sensors in the past, and those require no kind of reflector. Here is the review which details how to use them:



An example of a low cost photo electric sensor from ebay.

Good quality product. It has reverse polarity protection, etc. This has the emitter and receiver built-in. Best to use a retroreflector like a bicycle reflector or retroreflector tape. The indicator light will come on to show the state. The logic output is open collector and you'll get whatever the supply voltage is. To use with 5v ttl (using a second 5v source) wire as such:

Brown to +12V; Blue to ground; Pink to either +12 or ground depending whether you want Light-ON or Dark-ON mode;

Black to a 4.7K resistor with the other side of the resistor connected to a separate +5V source (the arduino). The 5v ttl signal is at the point where the black wire connects to the resistor.

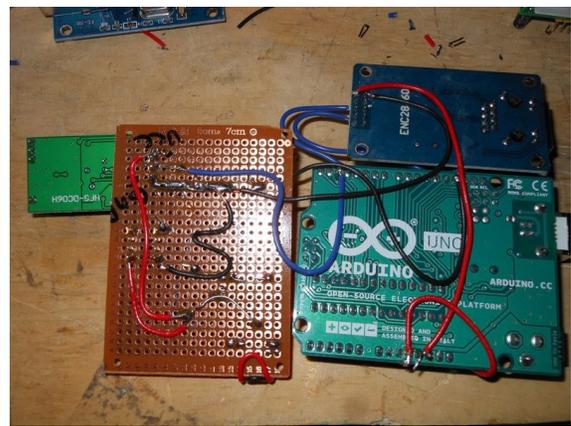
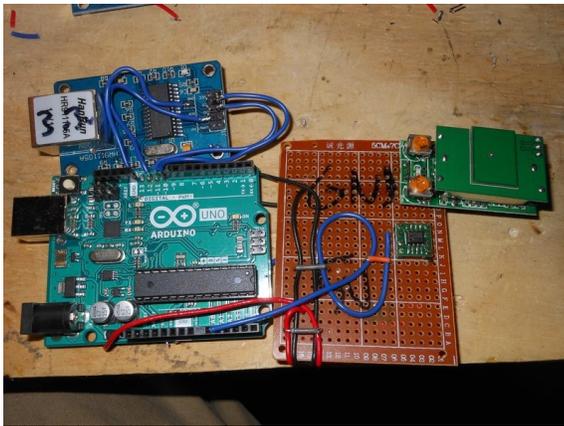
After trying with a component bag, which is slightly reflective, I was able to find a point where the emitter was consistently able to get a high result. This comment also tells you where to obtain the TTL

signal, we need for a micro to register a high. Therefore, I purchased some reflective stickers available from all electronics, as well as some iron-on reflective material from ebay. I will test both of these out next.

One thing I also noticed, was that used photo electric sensors from brand names can be obtained for discounts on the auction site. I saw a sick motion sensor for \$10. It may be wise in the future to look at auction sites, to see if a good deal can be had.

Revision 2 Using the HFS-DC06H Microwave Sensor

As I've tried with the HB100, without success, likely due to no included op amp (I tried throwing a cheapo one at it, but results were inconsistent), I've moved to the HFS microwave sensor. The code in the repo has been updated. I've also made a arduino uno shield layout to speed up assembly, which will be in this repo at some point. For now, perf board will do, while I wait for the boards to arrive.



During testing, I found that the HFS sensor would not work correctly with my laptops usb 2.0 power supply. I thought it might be RF interference from the metallic perf board – something I've seen before with the FM bug radio – but it was not. The solution was to use external power. See the four pictures (50mV/div). 1) with HFS powered direct from a bench PSU, 2) Arduino USB powered without HFS, but with ENC28J60 3) HFS from Arduino powered by USB (ENC+HFS), 4) from Arduino Uno with external 12V PSU (ENC+HFS).



The HFS draws negligible power, in this application, <5mA. The ENC on the other hand... (ethernet or wifi are around 200mA each, 3.3v). I suspect noise not capacity was the problem. Simply adding a capacitor to the HFS (I tried a 220uF name brand), did not resolve the issue. A worthy test would be an HFS with Arduino and no ENC. The usb power has limits that may be the culprit.

The HFS seems sensitive and responsive No false alarms upon initial testing. I use it at the shortest time setting on the potentiometer.